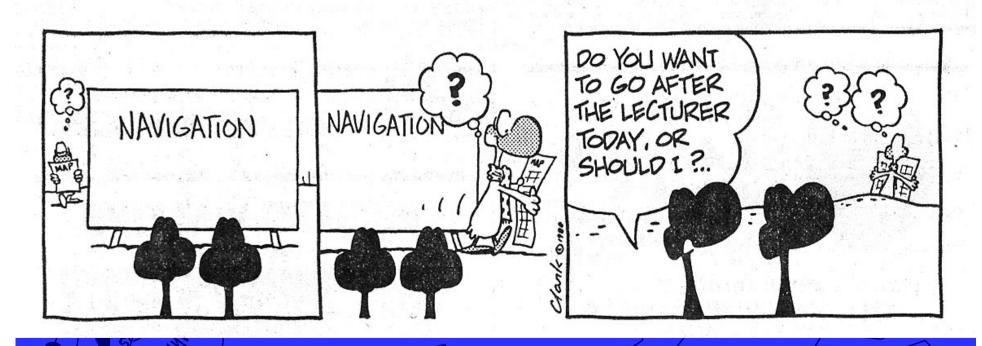
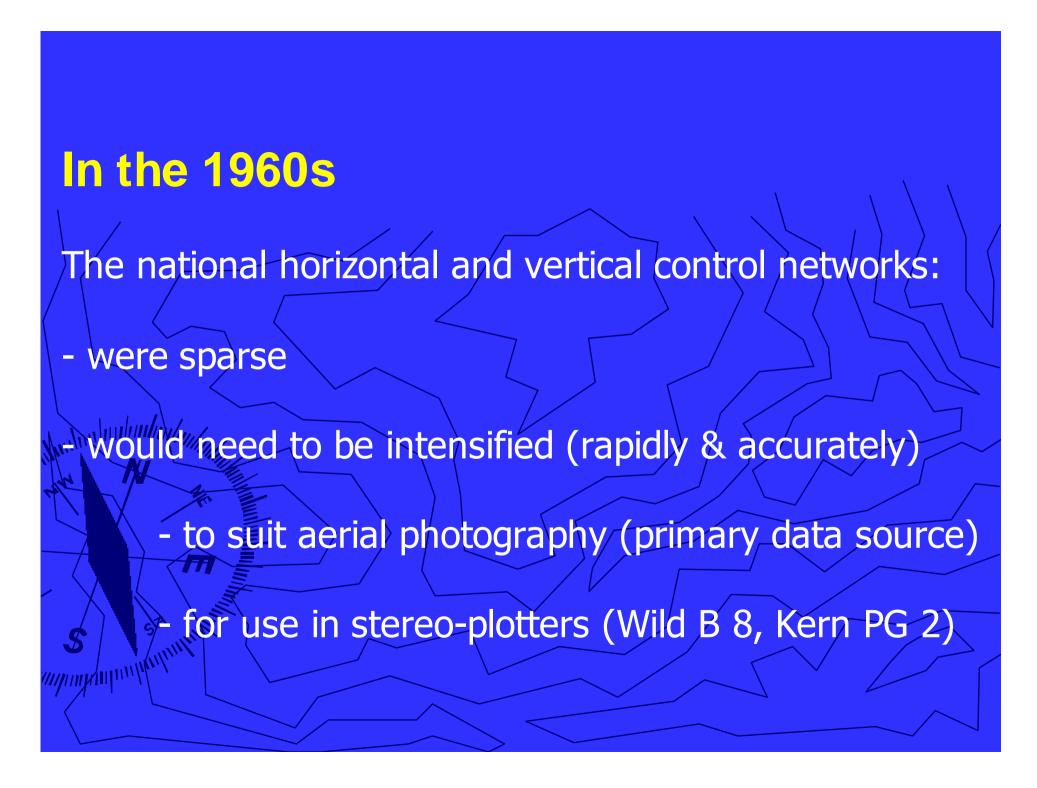


SWAMP by Gary Clark





Our paper describes the technology and processes Natmap used to fulfil this task using:

- 1 'Natmap early days, map compilation from aerial photographs 1948 1970s', by Dave Hocking.
- 2 Division of National Mapping Aerodist Program' Technical Report. No 27, by Carl McMaster
- 3 Laser Terrain Profiling', Division of National Mapping Technical Report No. 26, by Paul Wise

Remember that in the 1960s:

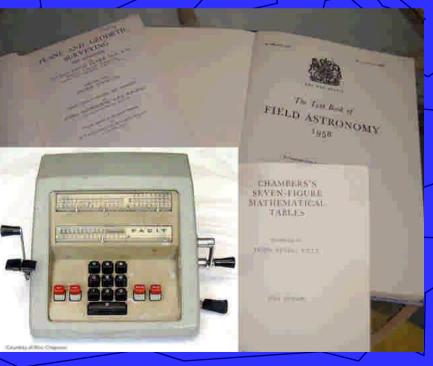
- the mobile phone

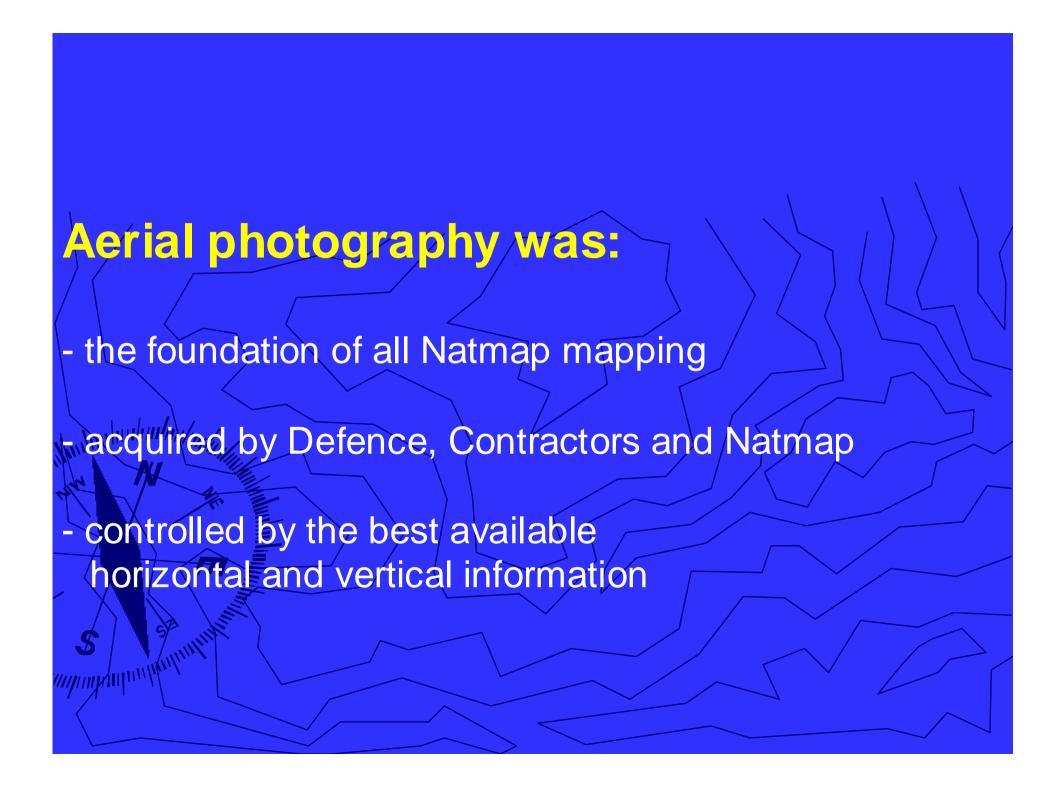
computer

- positioning system









I'LL EITHER HAVE TO GET A
LONGER FOCAL LENGTH
CAMERA OR FLY A BIT LOWER!



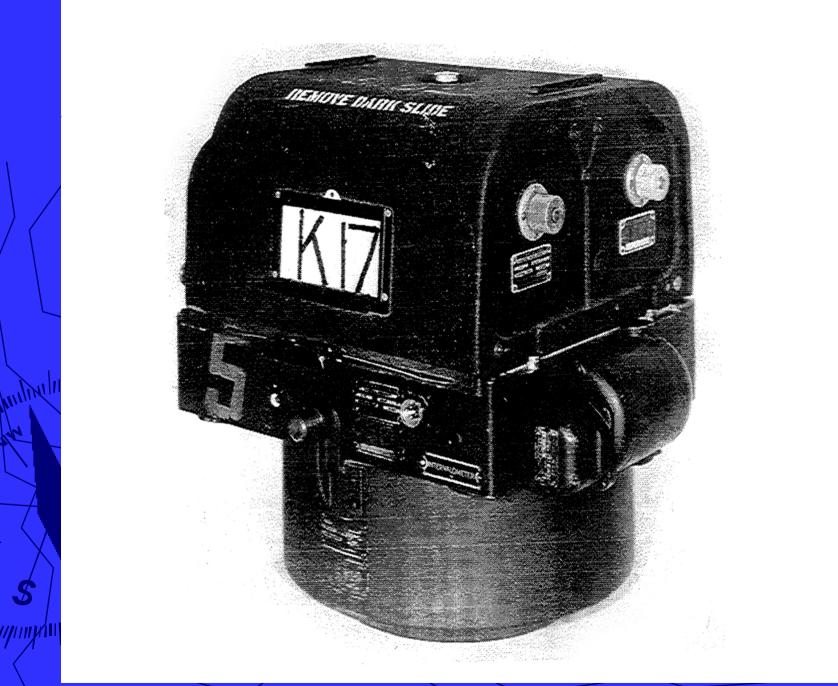


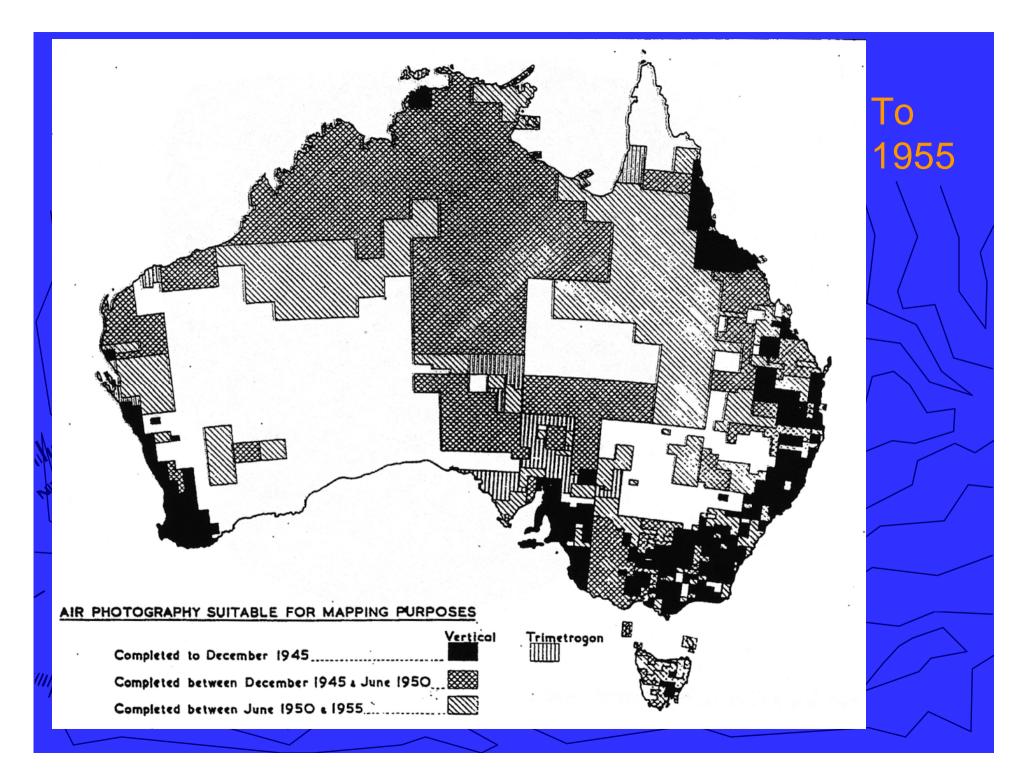


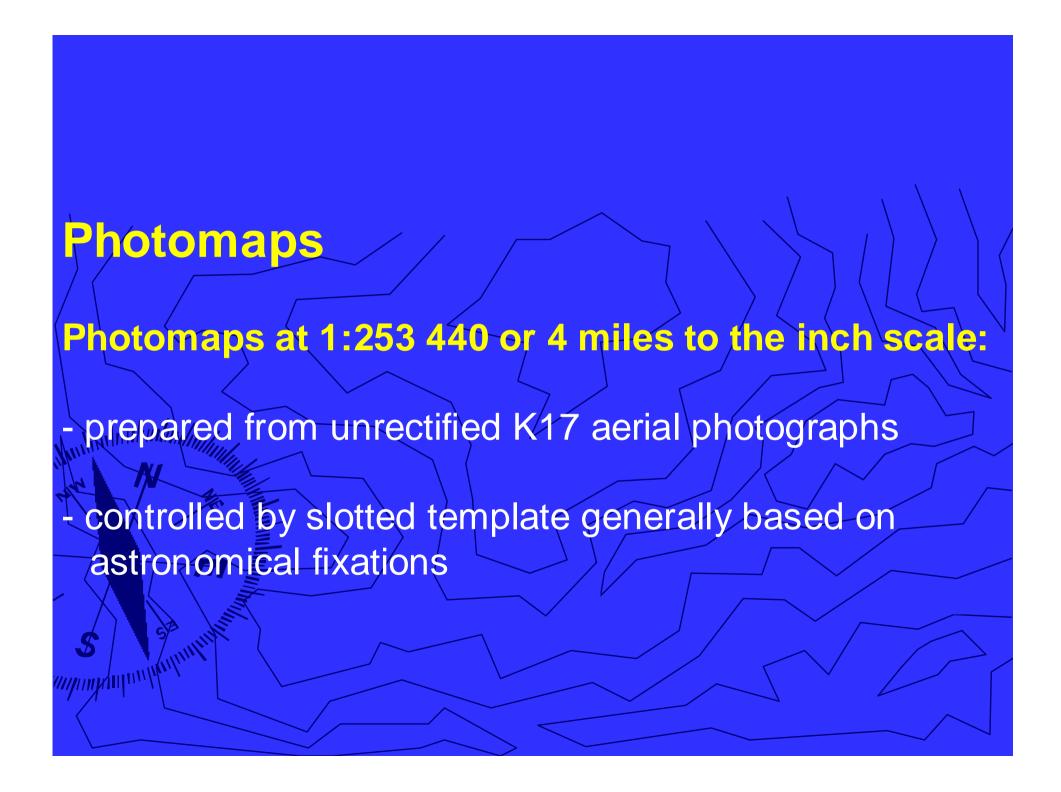
First of two eras of aerial photography

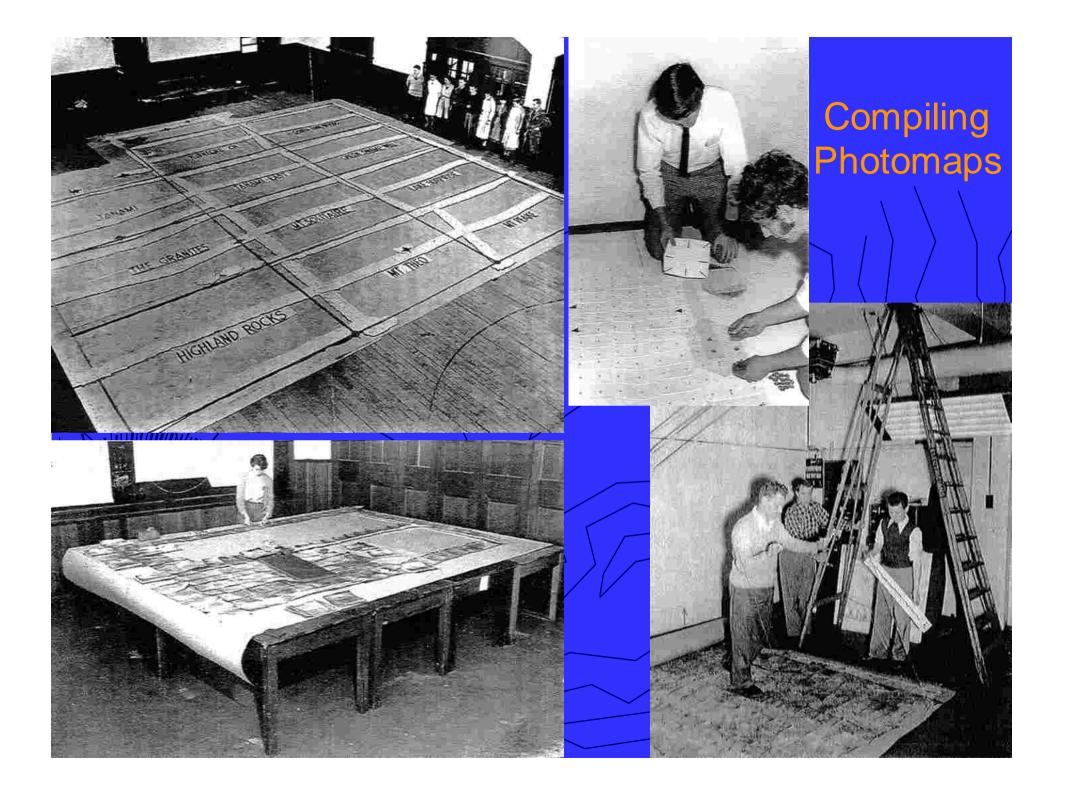
Late 1940s-early 1950s

- 1:50 000 scale with Fairchild K17 camera
- Obtained from 25 000 feet by RAAF, 87 PR
- (Photo Reconnaissance) Squadron
- Base data for the 1:253 440 and 1:250 000 scale R502 map series



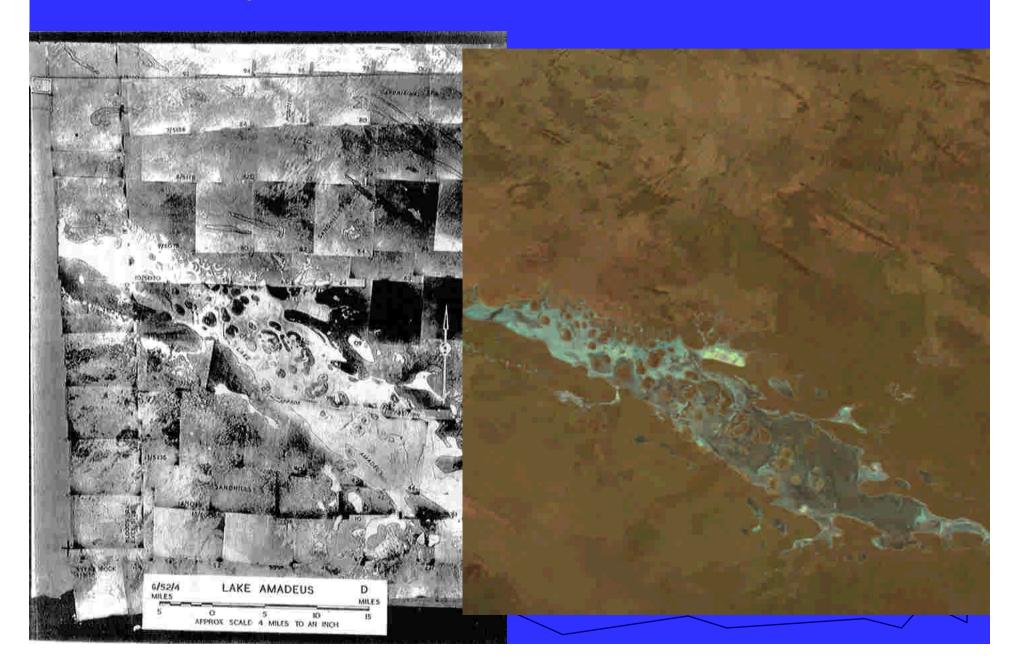






Photomap

Landsat ETM

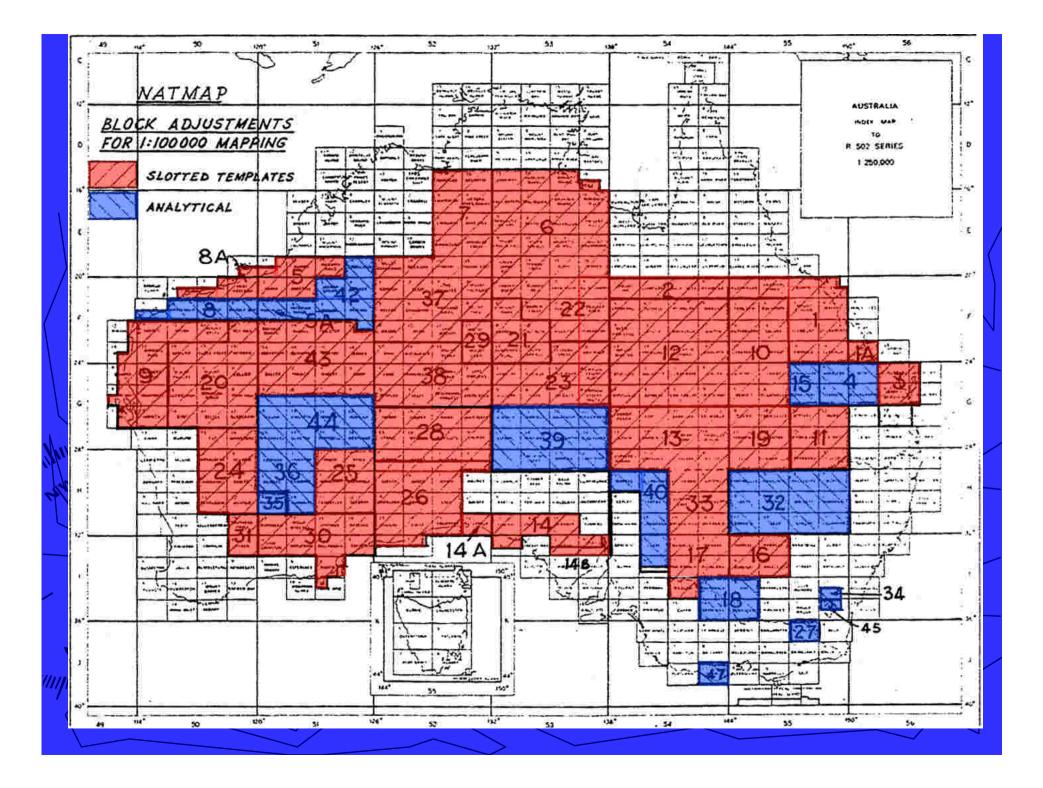


Second era of aerial photography:

Early 1960s – 1970s

- 1:80 000 scale with Wild RC9 or RC10 camera
- Obtained from 25 000 feet by contractors / Natmap
- Base data for the 1:100 000 and 1:250 000 scale National Topographic Map Series
- Controlled by slotted template generally based on first & second order survey control





Slotted Template Assembly (STA)

History

- Used by Natmap from 1948
- Typically a number of 1:250 000 scale map areas formed a STA "block"
- In 1970s in-house analytical aerotriangulation commenced
- By 1980s STA replaced by contract analytical aerotriangulation

Slotted Template Assembly (STA)

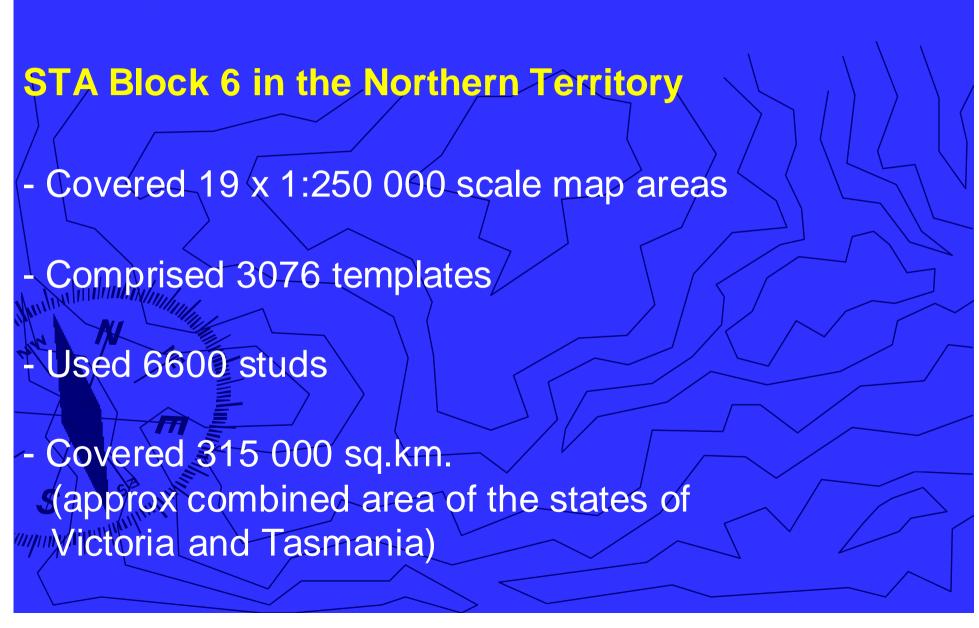
Advantages

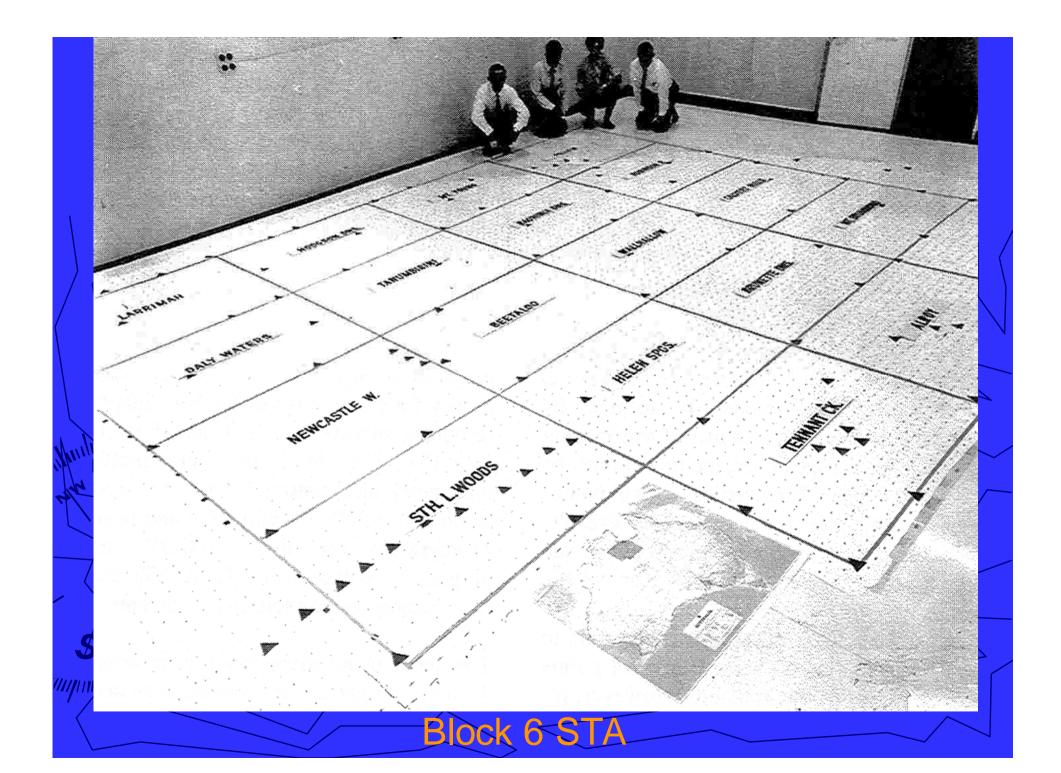
- Australia's inland undeveloped areas were relatively flat with slopes of less than 5 degrees
- Graphically determined horizontal control for each 1:80 000 scale stereo-model
- Gave direct transfer of minor horizontal control positions to compilation sheets

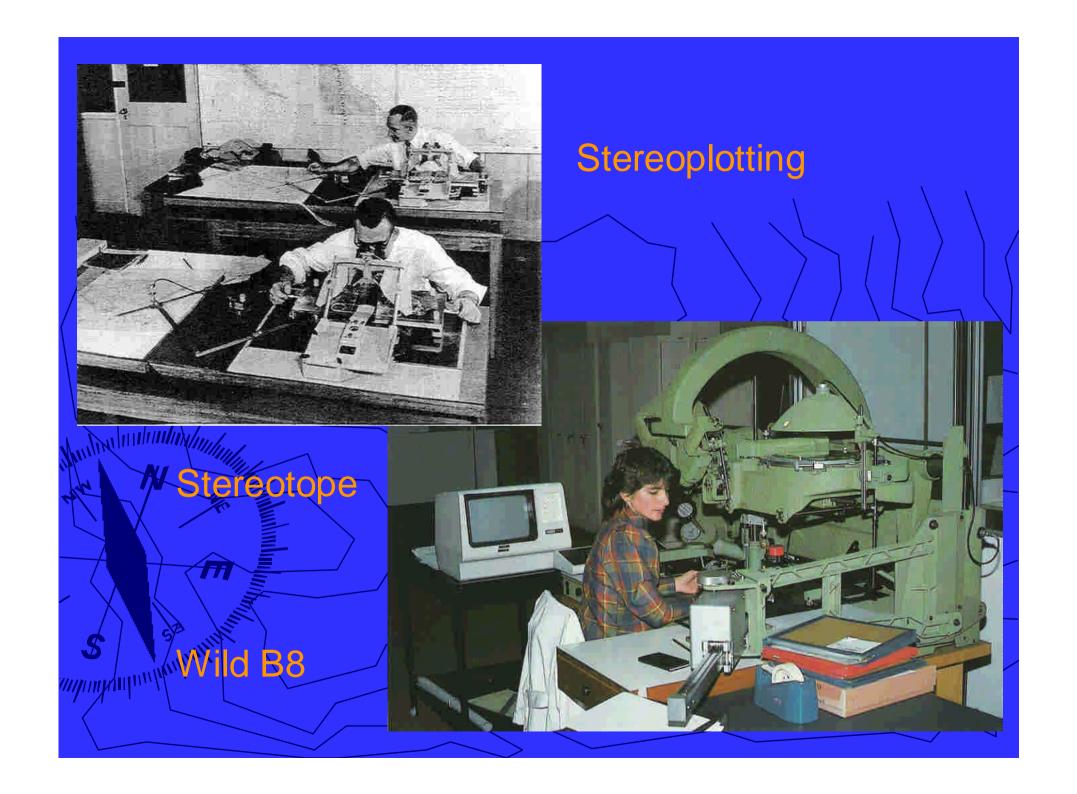


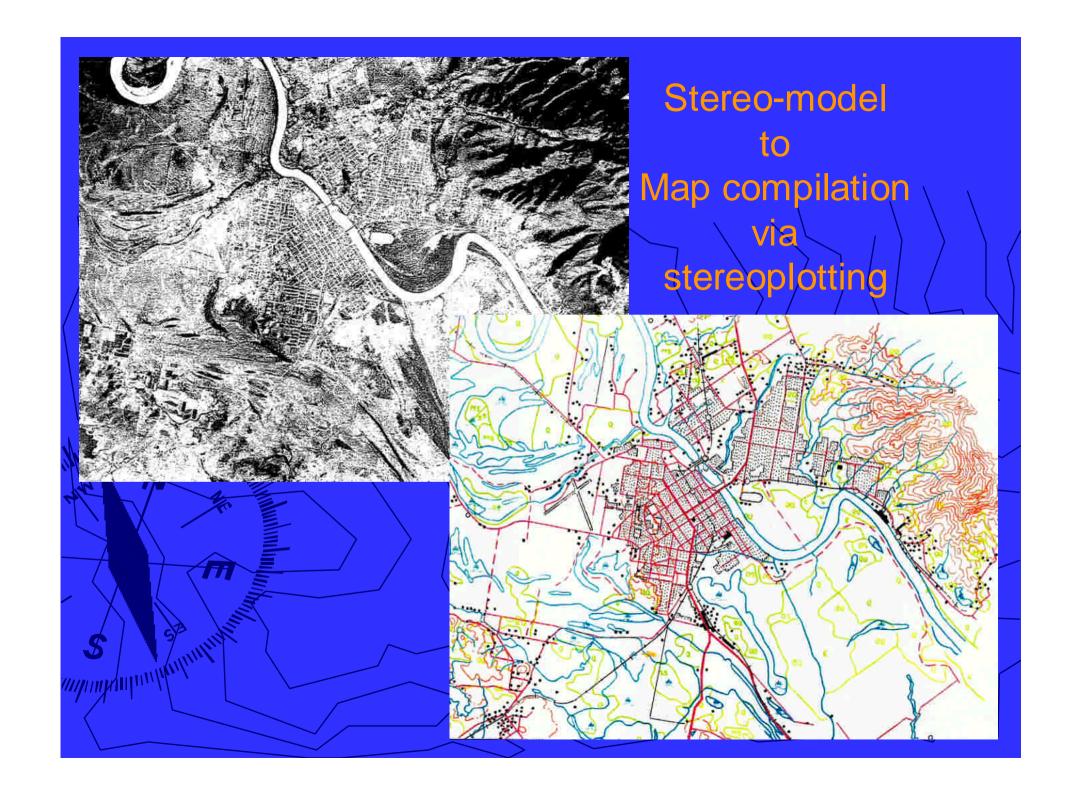
Example of a Stereo-model

Example











Horizontal control provided by:

- primary geodetic survey networks plus
 - astronomic observations &
 - identified survey marks

Vertical control provided by:

- 3rd order level traverses plus barometric heighting

To accelerate the mapping program Natmap introduced:

- Aerodist - Airborne distance measuring

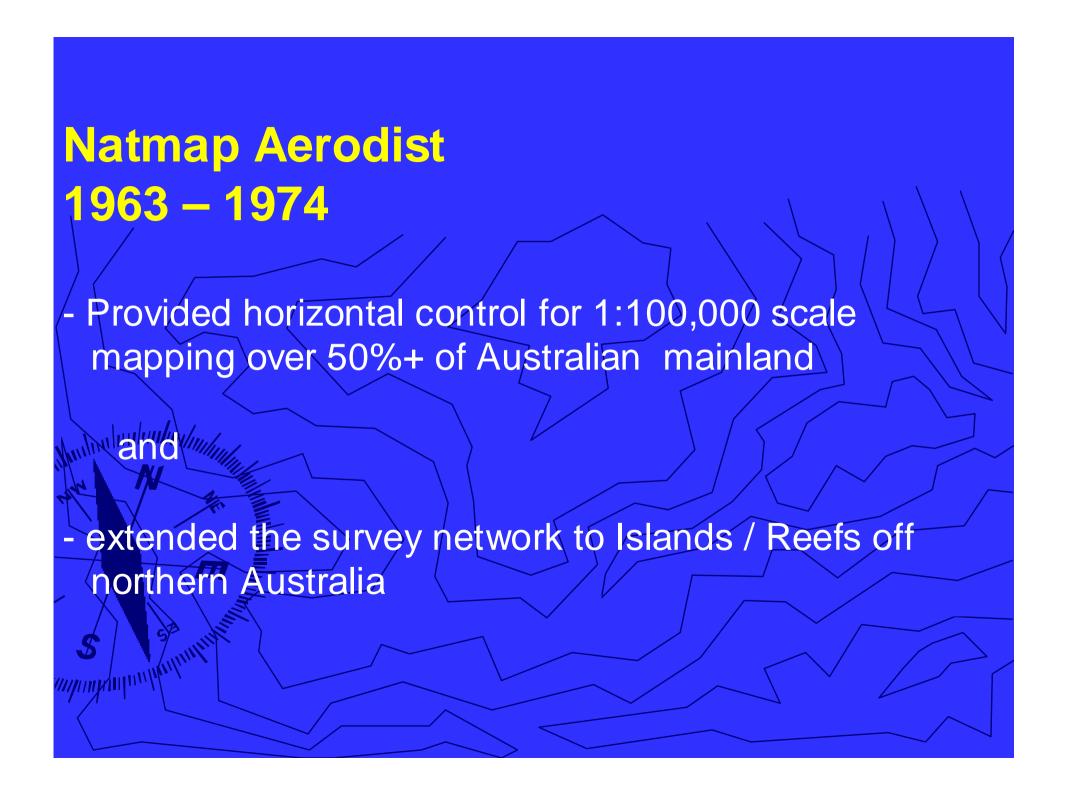
- Airborne profiling – APR – Airborne profile recorder

LTP – Laser terrain profiler

While "data gathering" was "state of the art" majority of data "reduction" was manual

Although labour intensive allowed errors to be trapped' and 'isolated' as they occurred

Errors did not accumulate



Before 1963

Sparse astronomical observations in-filled the geodetic survey network established by triangulation and EDM traversing

Astro obs accuracies (horizontal) ~ 30 metres

3rd order levelling and barometric heighting for vertical control

1:100 000 scale map program required horizontal control at:

- a minimum of 1 degree grid spacing
- an accuracy of ±3 m

Therefore needed to extend measuring range between non-intervisible points in flat areas of the continent

Thus Natmap purchasing approval in 1960 for an

Aerodist: airborne EDM (Fellurometer) system





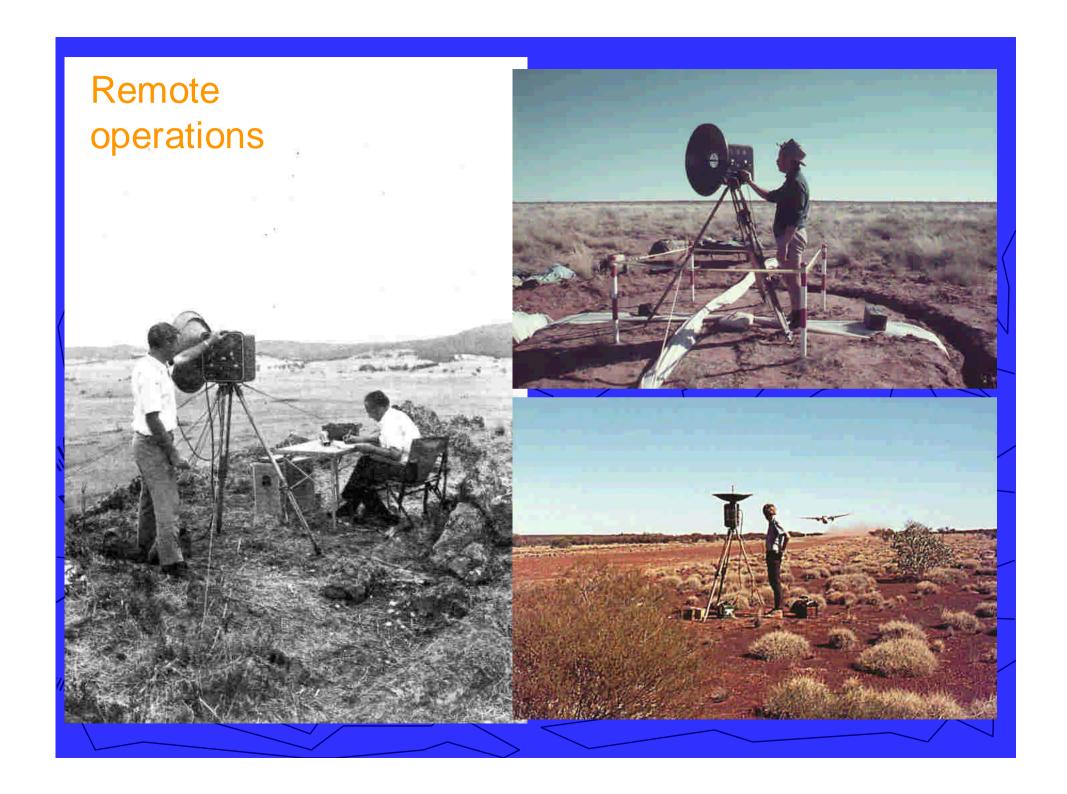


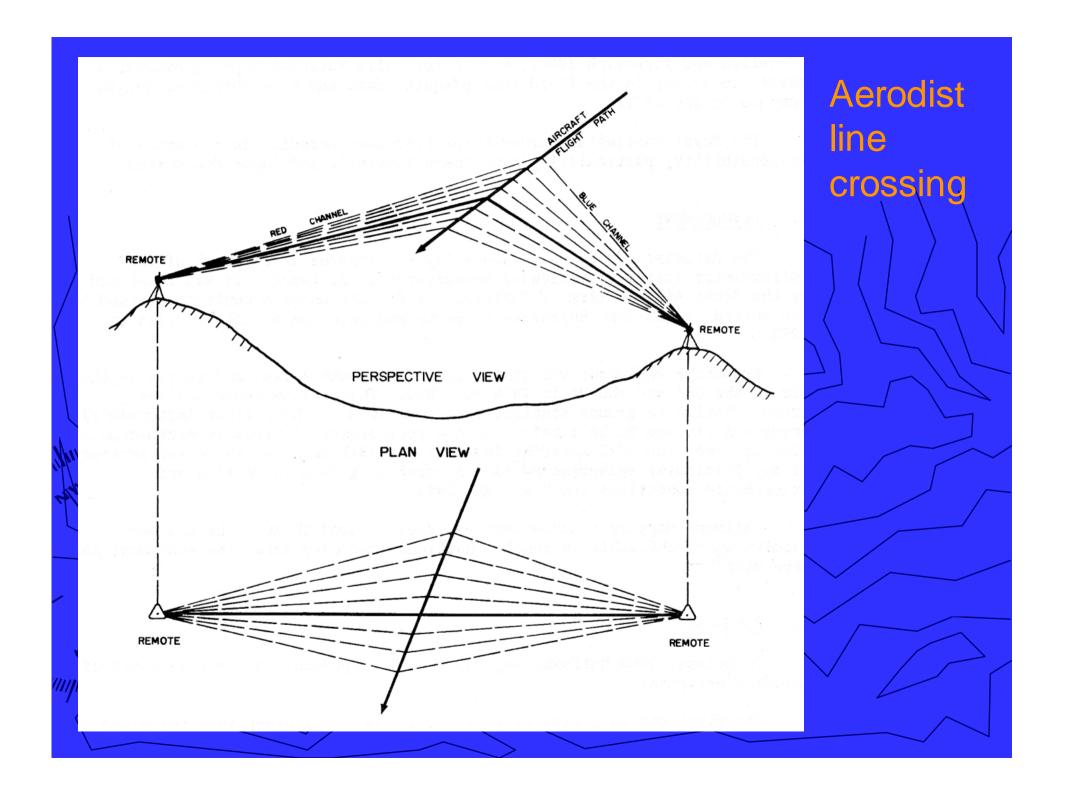
Original & later master antennae on Aero Commander aircraft

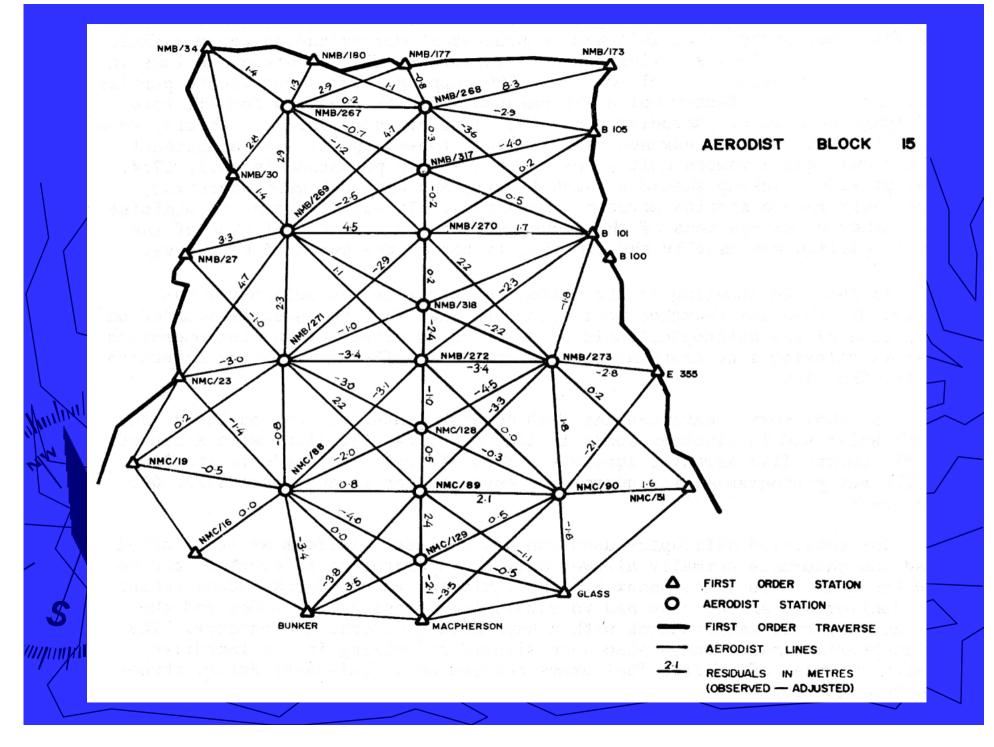


Master equipment rack in aircraft

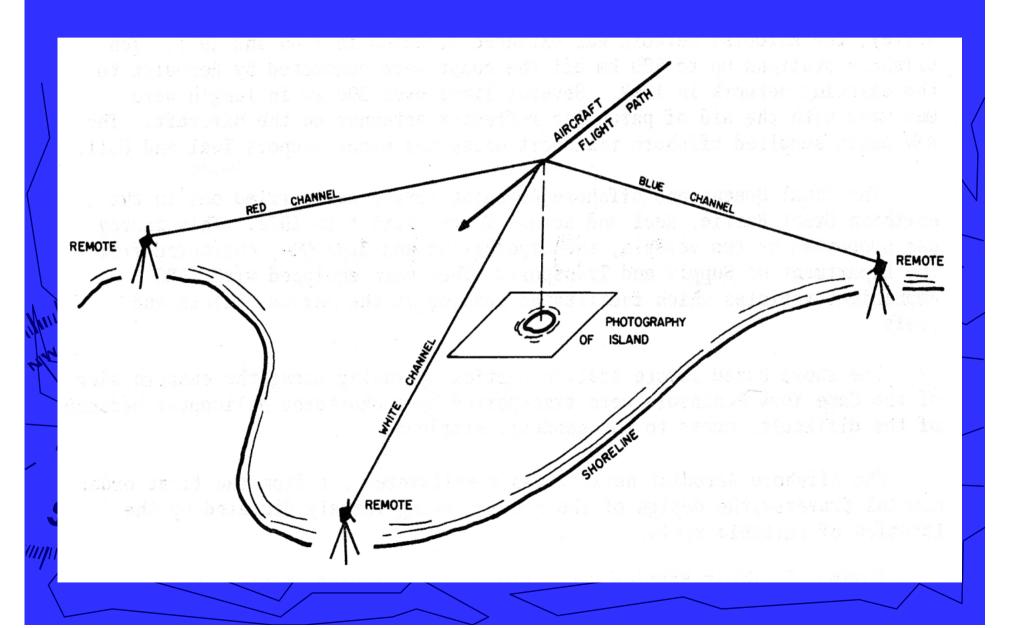








Aerodist trilateration



Aerodist Field Operations

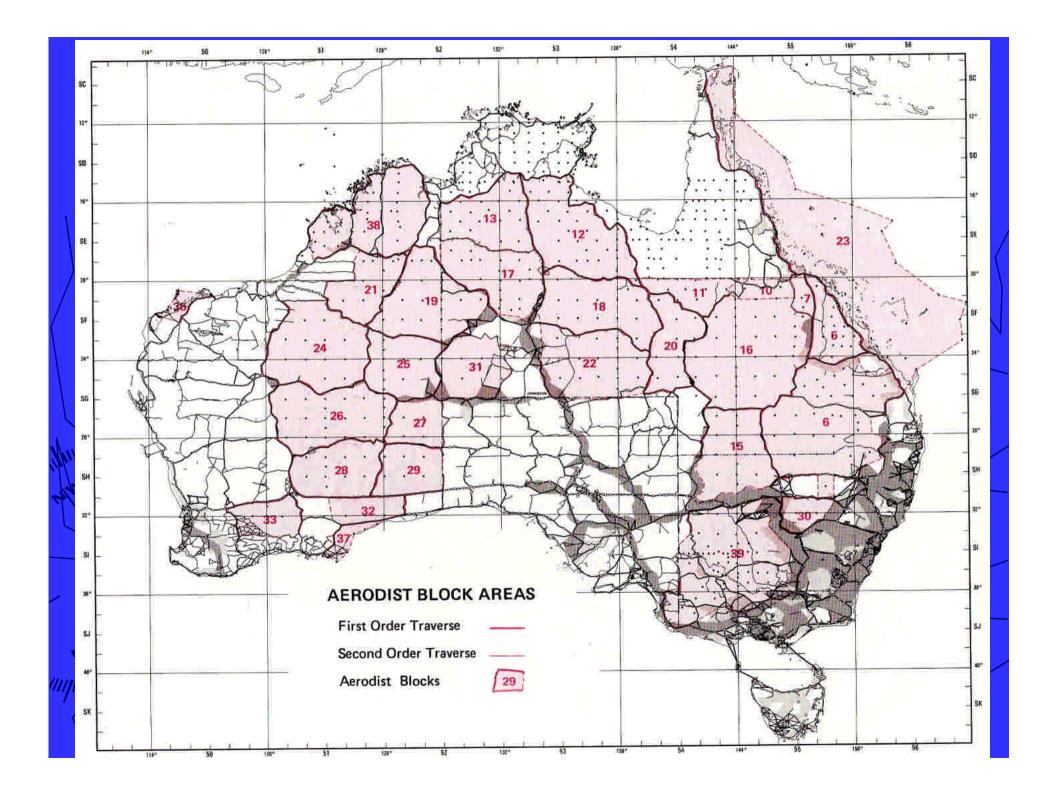
- Rapid and cost effective
- Key factors :
- planning vehicle movements
 - . Logistics (helicopter support)
 - communications (base station aircraft remotes)
 - "electronic equipment maintenance in field



- Survey skills + EDM operations and maintenance
- Electronic data processing for distance calculations
- Large scale block adjustments to fit perimeter geodetic control to provide AGD coordinates
- Software written in-house

Aerodist History

- 1961/62 Trials, Testing, Training in Bell 47J helicopter (from 1965 Aero Commander high-wing aircraft)
- 1963 Ten man survey party measured 66 lines to fix 17 stations in 6 weeks in SE Queensland
- Annual field surveys with 517 lines in 1972 measured in 34 weeks in WA from the Great Sandy Desert to the Nullarbor
- Program completed in 1974 with over 3000 lines measured to fix 480 stations

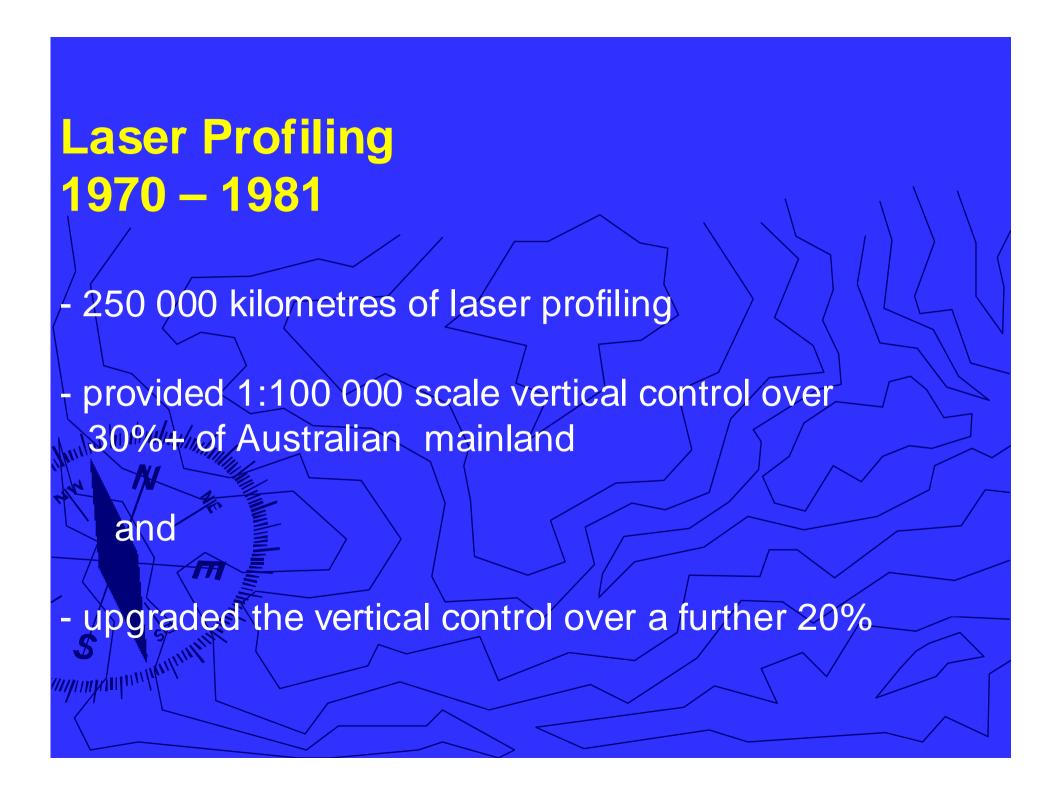


Aerodist Accuracy

- Aerodist Varycord adjustments gave an average difference between observed and adjusted distances of 1.49 metres for a 100 km line
- For the twenty-nine adjustments average maximum residual 6.3 metres (0.06 mm at 1:100 000 scale)
- Subsequent Tellurometer traverses or JMR fixes at Aerodist stations verified Aerodist coordinates to better than 5 metres







Before 1970

Vertical control initially provided by:

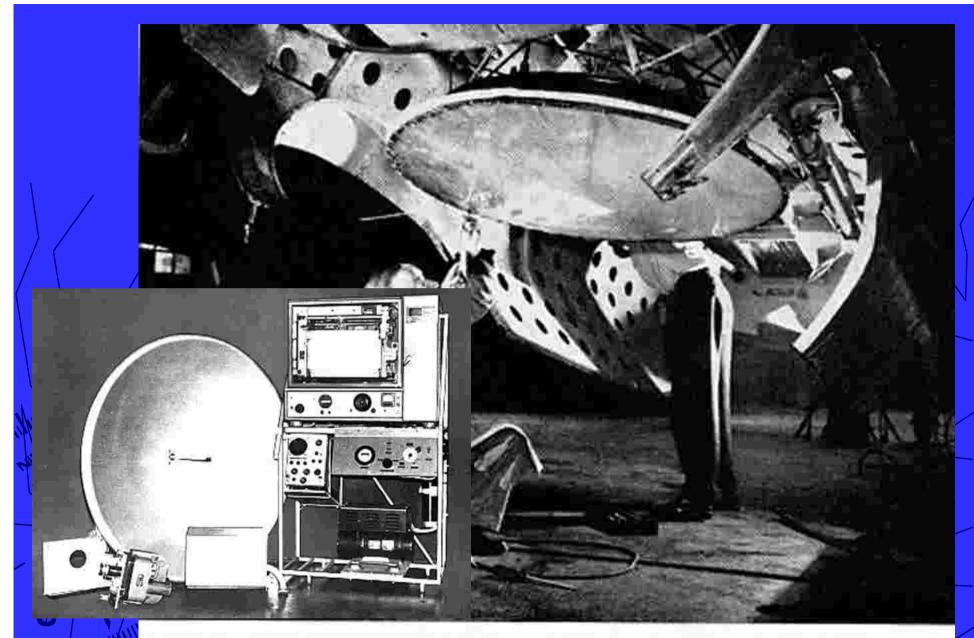
- 3rd order levelling
- barometric heighting

Subsequently:

July milling free

- Radar based Airborne Profile Recording (APR)

New laser technology provided more accurate system



Fitting the "dish" receiver for an Airborne Profile Recorder into a Lockheed Hudson,

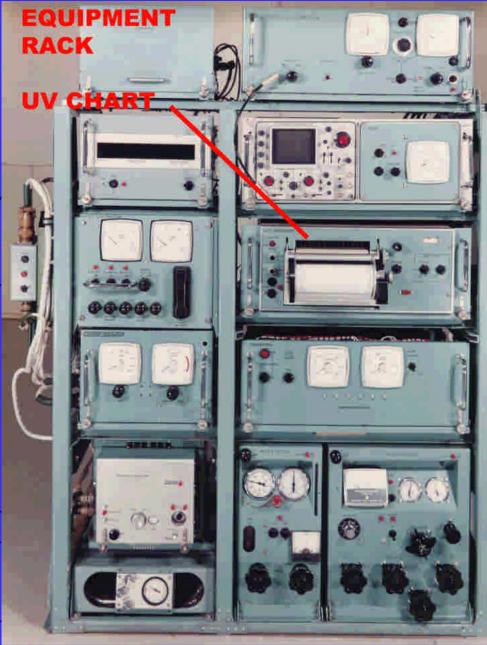
Airborne Profile Recorder (APR) System-

Laser Terrain Profiler (LTP) Components

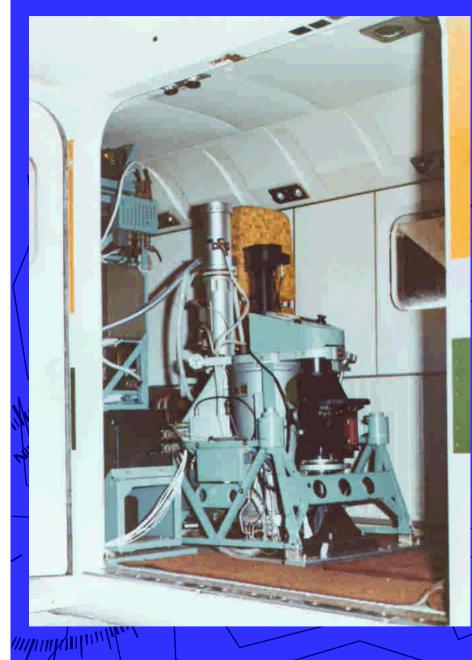
- Laser distance measuring system (laser emitter and receiver)

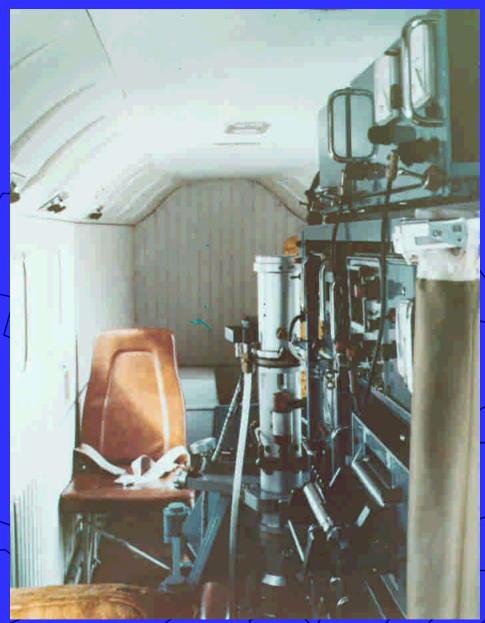
- Continuous-strip 70 mm camera to record the track
- Barometric reference unit to establish height datum
- Gyroscopes to sense the attitude of the aircraft
- Ultra-violet sensitive, paper recorder for data display



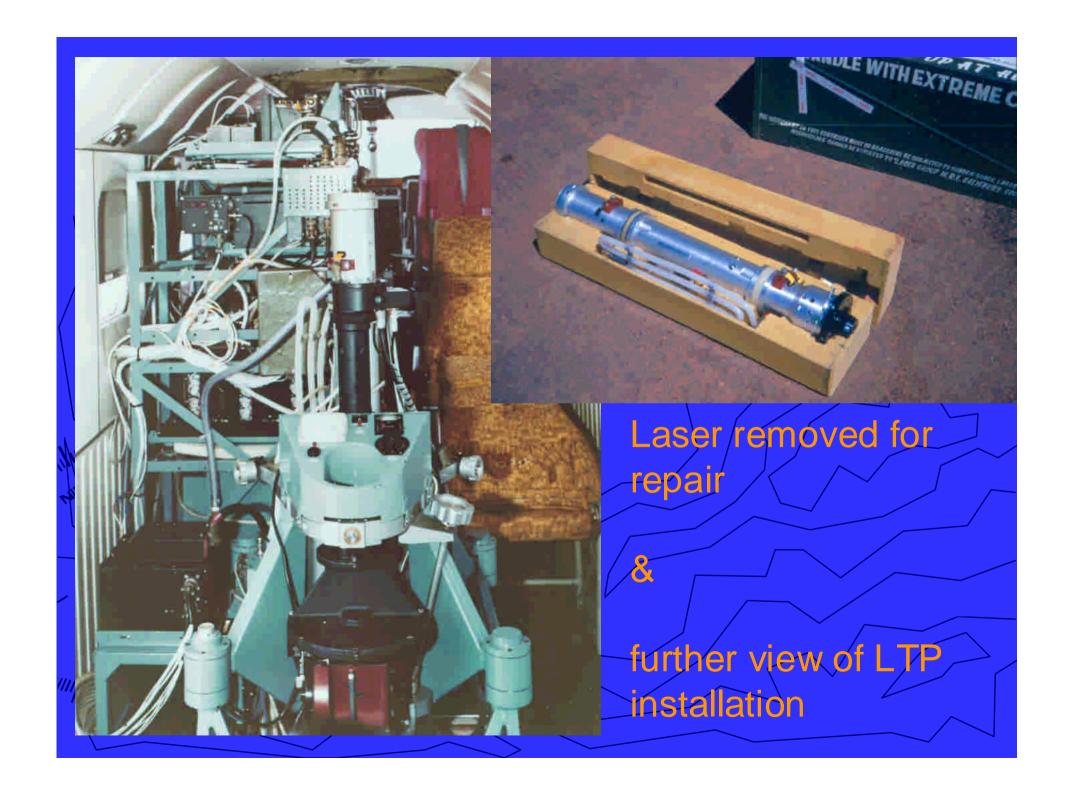


Laser Terrain Profiler (LTP) System-



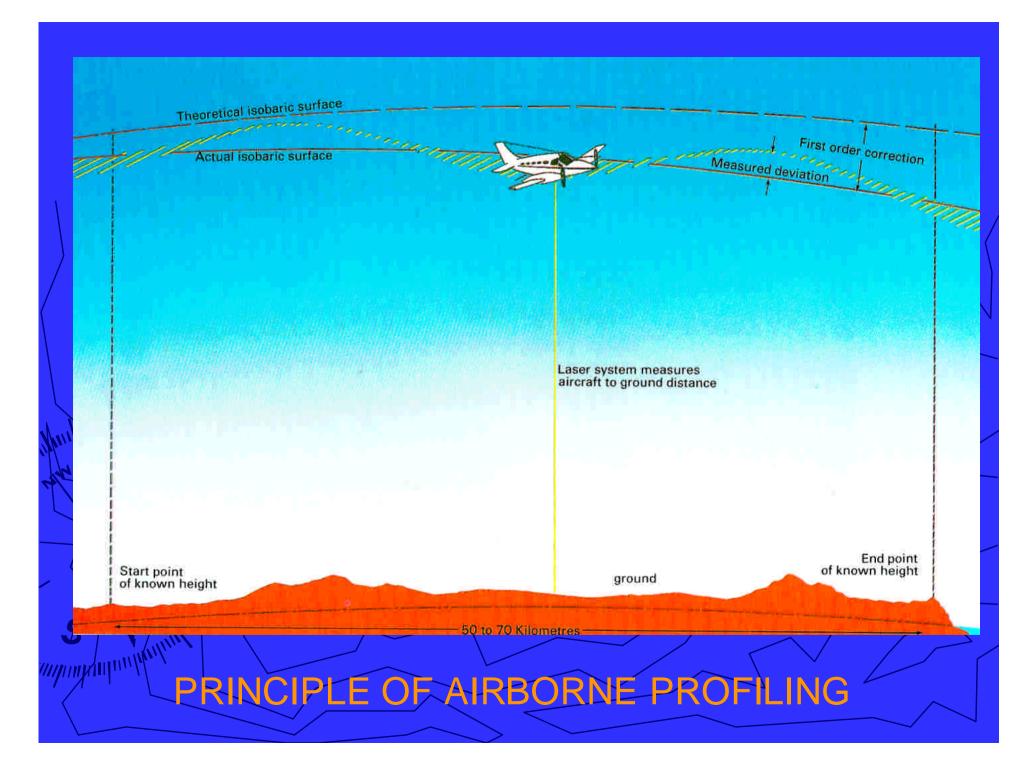


LTP System in NOMAD N22B

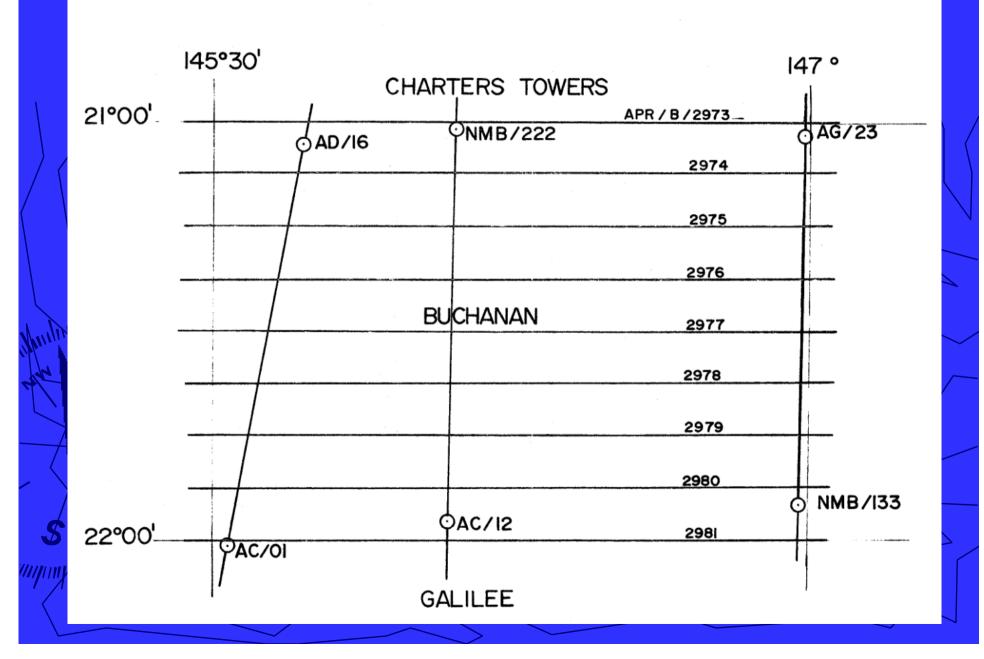


Principle of airborne profiling

- Fly along a pressure surface, continuously measuring any deviation from that surface (Δd) and the distance between the ground and aircraft (d)
- Using points of known elevation at the start and finish of each flight line establish the flight height datum (h) and any misclose (Δh)
- The height of any intermediate point is the flight height datum less the sum of the other components $(h)^{\mu\nu}(\Delta h + d + \Delta d)$



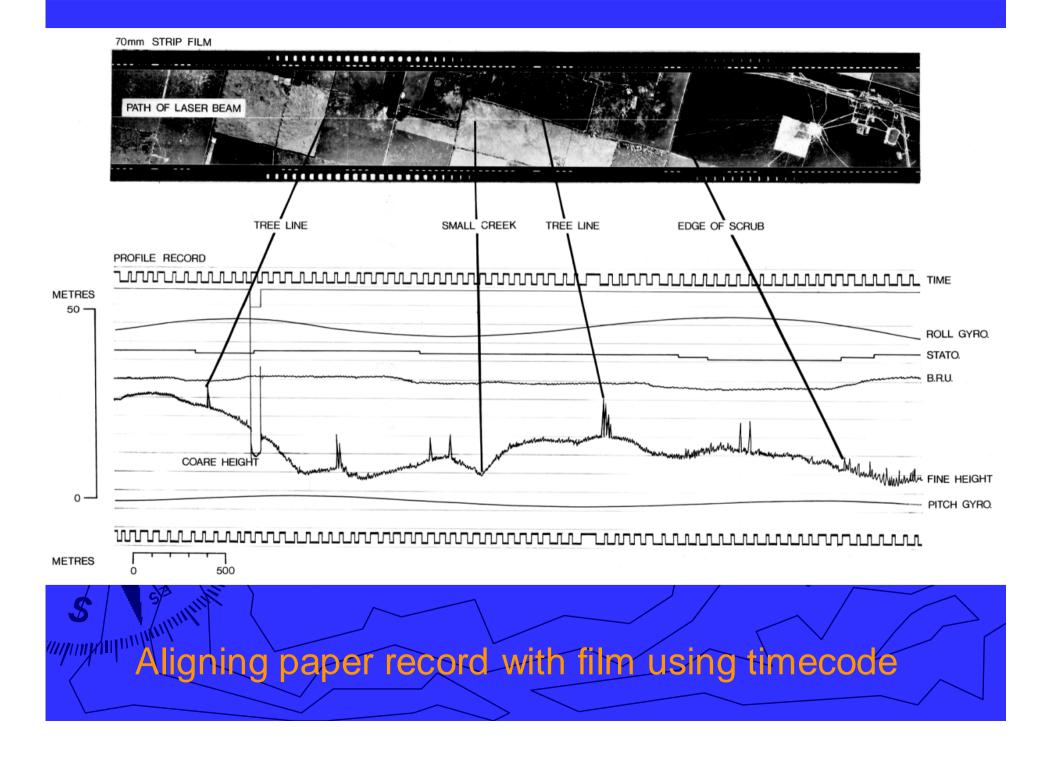
LTP SURVEY BUCHANAN

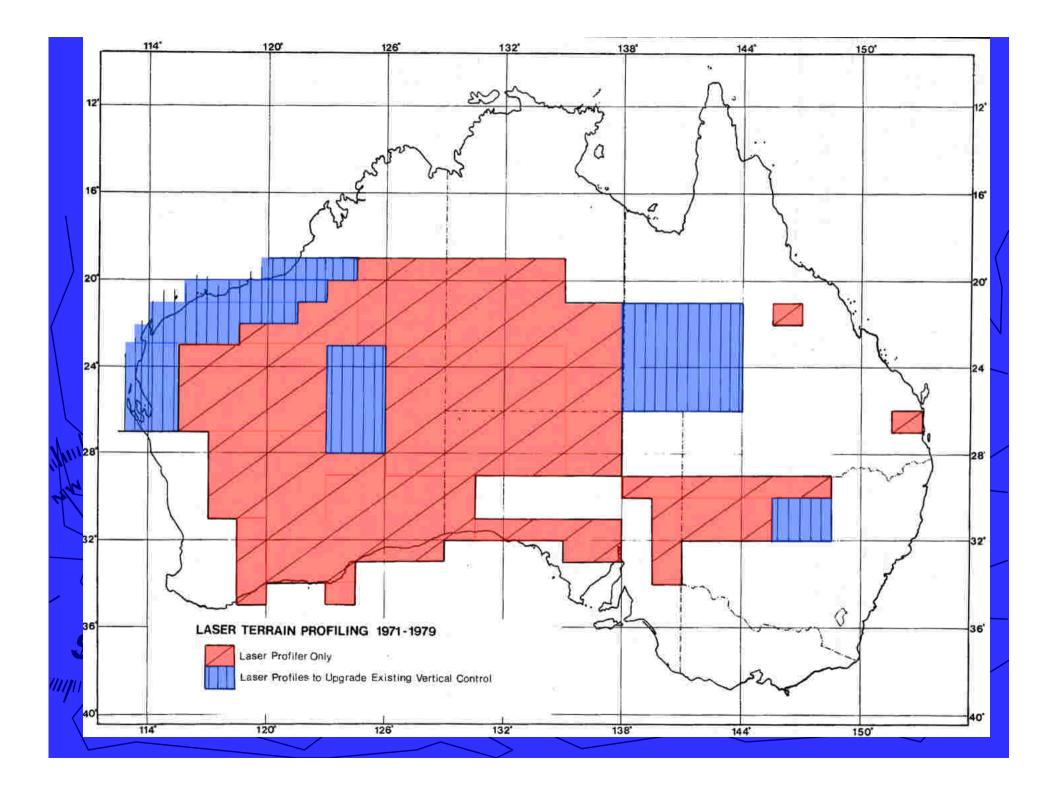


Heights for stereo-model control

For each stereo-model

- common points of detail from 70 mm tracking camera film selected and annotated
- aligning the time code on the edge of the film with that on the paper roll recorder relate the two media
- the height of a point is calculated from data extracted from the paper record at the applicable time





LTP Accuracy

- Laser accuracy ±0.3 m at all times
- Cumulative system errors decrease accuracy to ±3 m
- In practice, ±2m expected
- This is about the pointing accuracy of the photogrammetric plotters used on 1:80 000 scale photography, so the two systems are compatible





Quote (17 December 1979) (At the end of the laser profiling field program)

- "Looking back it amazes me that the combination of:
 - (a) Weather including high and low clouds
 - (b) Aircraft unserviceability and pilot's hours
 - (c) Equipment including leaky lasers, modulator bubbles and electronic gremlins
 - (d) Personnel including lost navigators, operators jamming camera cassettes, technicians blowing capacitors,
- compounded by turbulence, cross winds, hail, fuel drums, fuel pumps, refuelling difficulties and late nights and early mornings that any profiling was ever done at all."

Map Accuracy Natmap maps

Measured by:

- 'completeness' (fidelity of representation and description of the topographic features represented)
- metric quality' (the correct geographical positioning of the topographic features represented)

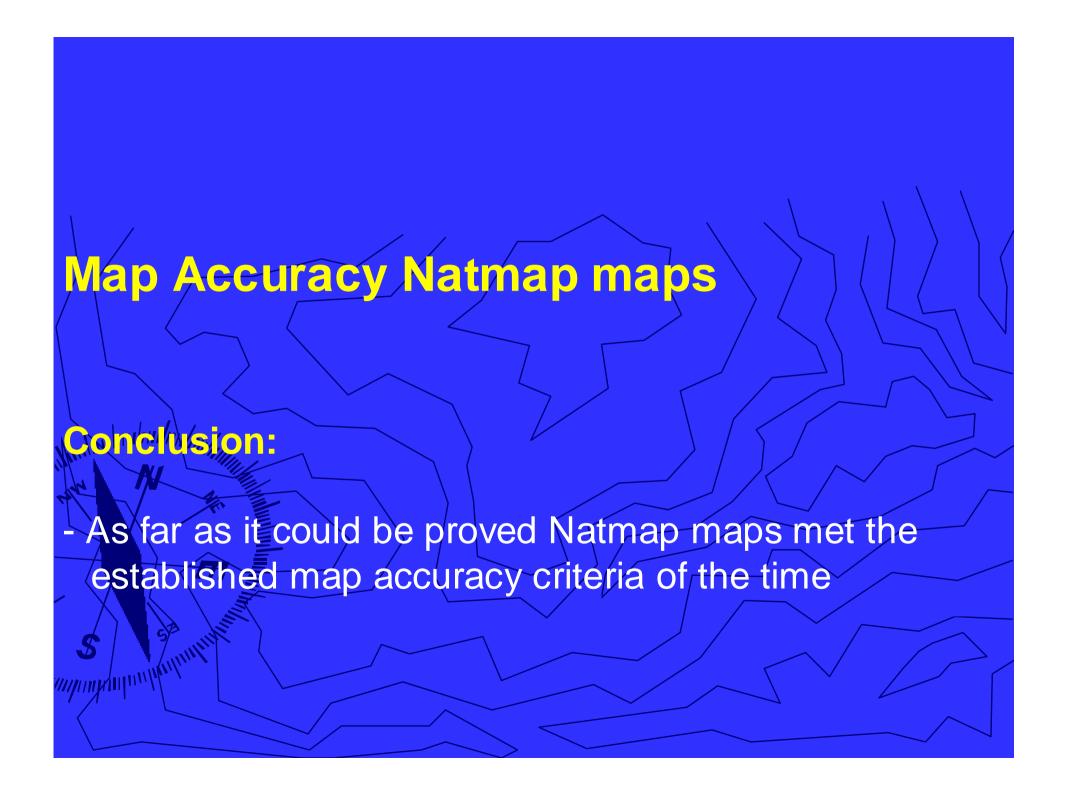
Completeness surveys:

carried out by air and ground methods

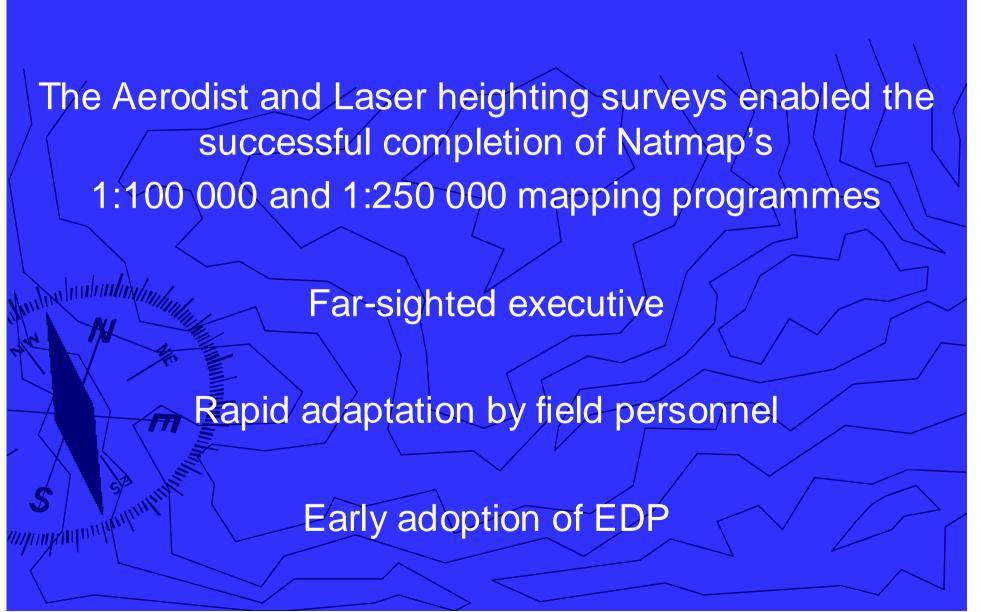
Map Accuracy Natmap maps

Metric quality:

- Ascertained on a sampling basis
- A representative map selected from block of maps based on common horizontal & vertical control
- Positions of 'check' points independently established by ground survey & compared with the map coordinates







The Authors gratefully acknowledge the following:

- the Australian Map Circle
- Mrs Iris Hocking allowing us to use Dave's paper
- the Commonwealth of Australia, through Geoscience Australia for the use of the Natmap papers
- so as not to leave anyone out, all those who worked for or with Natmap, for their contribution to mapping
- Messrs Ely, Ertok, Lawrence & Stuchbery